# **SEM110**

## TEMPERATURE TRANSMITTER





Important - Read this document before installing.

IMPORTANT - CF. LIKCA & SAFETY REQUIREMENTS

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#### 1.0 GENERAL

The SEM110 series are high performance two wire (4 to 20) mA transmitters designed to accept most standard industrial temperature thermocouple, slide wire and variable resistance sensors which operate over most common ranges. Automatic thermocouple cold junction compensation is provided on thermocouple versions where the output is directly referenced to the mV input, allowing linearisation to be carried out by the loop monitoring instrumentation, if required. The device is potted inside a plastic enclosure, suitable for head mounting into any DIN style enclosure. Screw terminals are provided for wire connections. Trim potentiometers are provided to allow calibration adjustments.

#### 2.0 SEM110 SPECIFICATION @ 20 °C

Part Number Input Type

Isolated (Un-grounded) Thermocouple types SEM110TC

K.T.J.R.S.N

SEM110P PT100, PT10, PT1000

SEM110W Slide Wire

SEM110Z Variable resistance

SEM110D Differential PT100

OUTPUT (4 to 20) mA two wire (Max 30 mA)

SUPPLY VOLTAGE (10 to 45) V DC reverse connection protected.

30 VDC Max I.S. version

AMBIENT TEMP (0 to 70) °C operation

(-40 to 100) °C storage

AMBIENT HUMIDITY (0 to 95) % (non-condensing)

CONNECTION Screw Terminal

Recommended cable size 2.5 mm sq.

7FRO DRIFT ±2 µA/°C

SPAN DRIFT +0.01 %/°C

LOOP RESISTANCE 700 R Max (24 V)

**EMC** Conforms to BS EN 61326

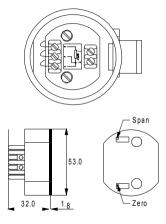
#### 3.0 INSTALLATION

#### 3.1 Mechanical

The transmitter is mounted using two 4.5 mm diameter holes, on standard 33 mm fixing centers. This transmitter has been specifically designed to be mounted inside a DIN standard probe head, which must provide adequate protection to moisture, corrosive atmospheres etc. All cable entries should be sealed using the correct size cable gland.

Care must be taken when locating the transmitter to ensure the ambient temperature remains inside the specified range of (0 to 70) °C. The diagram shows the mechanical layout with a typical application of the transmitter mounted inside a probe head enclosure

Mounting Holes: 2 Holes 4.5 mm Diameter, 33 mm Centers



### 3.2 Electrical

Connections to the transmitter are made to the screw terminals provided on the top face.

The SEM110 conforms to BS EN 61326 and as such, the radiated electromagnetic susceptibility is tested to 3 v/m. It is therefore recommended that during the installation process, the instrument should be mounted away from any high-powered radio transmitters and away from any heavy switching gear.

To maintain EMC compliance input/sensor wires must be less than 3 meters long and output wiring must use screened twisted pair cable with the screen earthed at one end only.

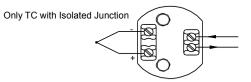
All three input wires must have the same core diameter to maintain equal lead resistance in each wire. T/C sensors must be ungrounded.

The transmitter is protected against reverse connection by means of a series diode, therefore incorrect connection of the output wires will result in near zero current flow in the loop. Incorrect connection or failure of the sensor wires will result in the transmitter saturating, T/C versions go

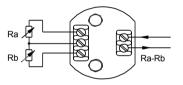
upscale, whilst resistance sensor inputs go either upscale or downscale dependent upon which wire breaks. The most common failure would be a total sensor burnout in which case the transmitter will go upscale.

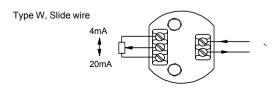
#### 3.3 connections

Pt 100 3 Wire

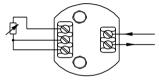


Type D. Differential Temperature





Type Z. Variable Resistor



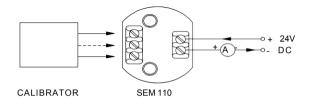
The diagram shows the method of connection to provide a (4 to 20) mA current loop output.

The Pt100 sensor shown as an example would normally take the form of a probe assembly with a three-wire output. Refer to connection drawing for other connection types. The output loop shows a 24 V DC power supply used to provide loop excitation, the transmitter and a load all connected in series. The load symbol represents other equipment in the loop e.g. indicators, controllers, loggers etc. Sometimes these instruments come with the 24 V supply built in as standard, this simplifies wiring and reduces cost. Care must be taken when designing the (4 to 20) mA circuit to ensure that the total burden of the loop, that is the total voltage requirements of all the equipment in the loop added together, does not exceed the power supply voltage. If a number of instruments are connected in the loop, ensure that only one instrument is tied to ground. Grounding the loop at two points will result in shorting out part of the loop and therefore any instruments in that part of the loop will not operate.

#### 4.0 Calibration

Calibration is only recommended when the user has access to suitable equipment, together with a reasonable knowledge of instrumentation calibration techniques. The following instructions act as a guideline to calibration.

- 4.1 A precision calibrator will be required, to simulate the type of sensor the transmitter is designed for, together with a set of tables giving the sensor output against process variable, (e.g. resistance against temperature for a PT100 sensor). A precision digital current meter together with a 24 V DC supply will also be needed. Read the SEM110 label to establish the transmitter range i.e. the process variable input for 4 mA and 20 mA. The side label also indicates the location of the span and zero pots.
- 4.2 Connect calibrator to input terminals, using the correct compensation wire for thermocouples inputs and three wire connection for RTD inputs. Connect the output positive to +24 V, negative to 0 V via current meter. Turn power on.
- 4.3 Set simulator to 4 mA process variable and adjust ZERO trimmer for 4.000 mA output. ±0.002mA
- 4.4 Set simulator to 20 mA process variable and adjust SPAN trimmer for 20.000 mA output ±0.002 mA.
- 4.5 Repeat steps 4.3 and 4.4 until both points are in calibration.
- 4.6 Turn power off and remove calibration equipment.



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